

# Areal Data and Proximity

HES 505 Fall 2024: Session 19

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# Objectives

By the end of today you should be able to:

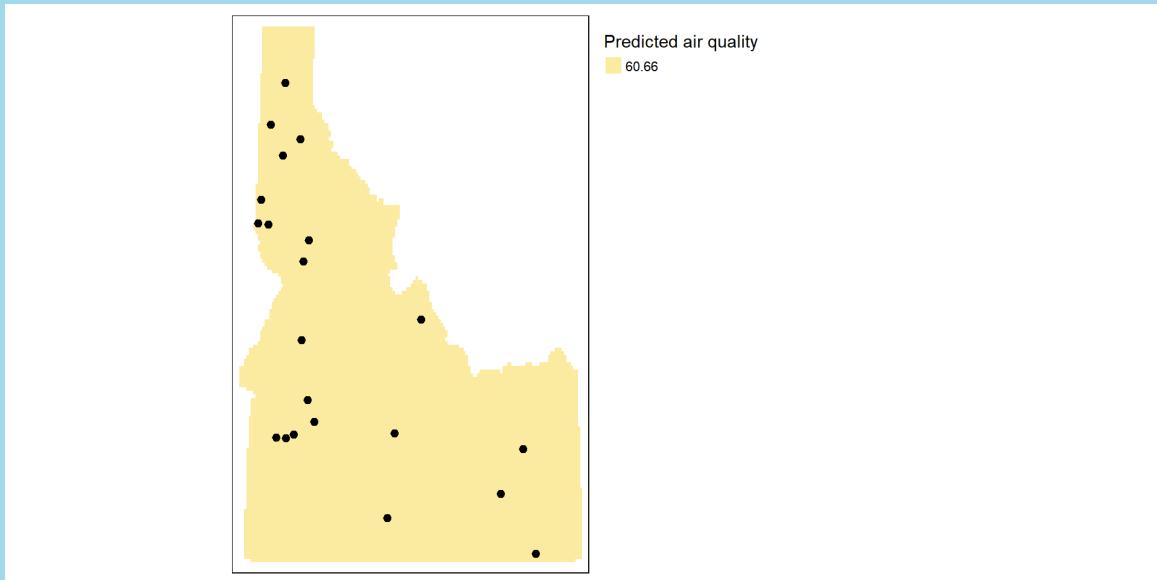
# Statistical Interpolation

# Statistical Interpolation

# Trend Surface Modeling

- Basically a regression on the coordinates of your data points
- Coefficients apply to the coordinates and their interaction
- Relies on different functional forms

# 0th Order Trend Surface



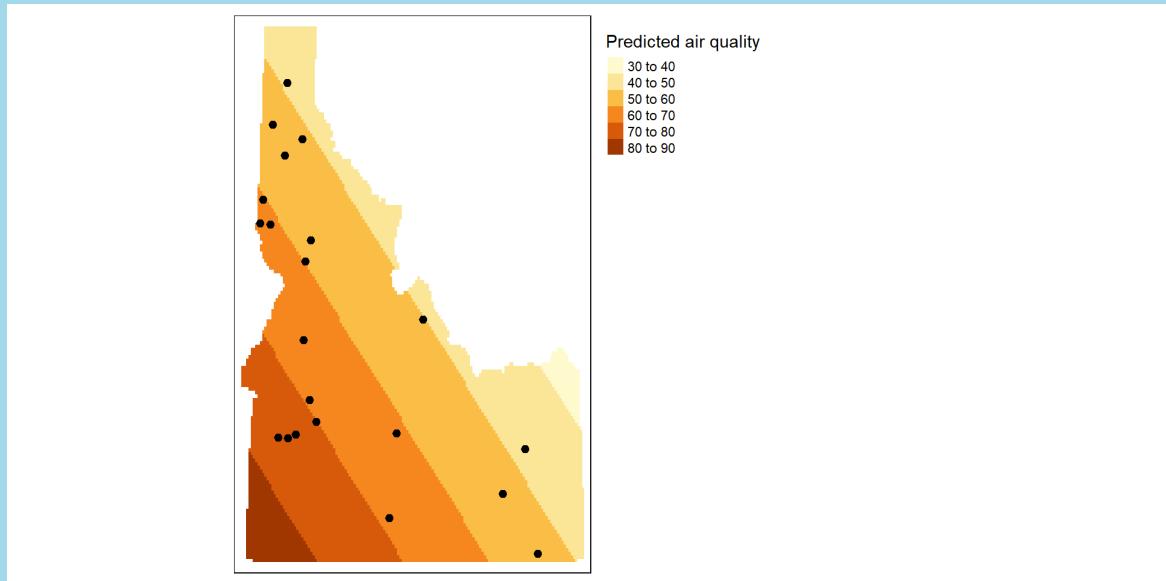
- Simplest form of trend surface
- $Z = a$  where  $a$  is the mean value of air quality
- Result is a simple horizontal surface where all values are the same.

# 0th order trend surface

```
1 #set up interpolation grid
2 # Create an empty grid where n is the total number of cells
3 bbox <- st_bbox(id.cty)
4 grd <- st_make_grid(id.cty, n=150,
5                         what = "centers") %>%
6   st_as_sf() %>%
7   mutate(X = st_coordinates(.)[, 1],
8         Y = st_coordinates(.)[, 2])
9
10 # Define the polynomial equation
11 f.0 <- as.formula(meanpm25 ~ 1)
12
13 # Run the regression model
14 lm.0 <- lm( f.0 , data=aq.sum)
15
16 # Use the regression model output to interpolate the surface
17 grd$var0.pred <- predict(lm.0, newdata = grd)
18 # Use data.frame without geometry to convert to raster
```

# 1st Order Trend Surface

- Creates a slanted surface
- $Z = a + bX + cY$
- X and Y are the coordinate pairs

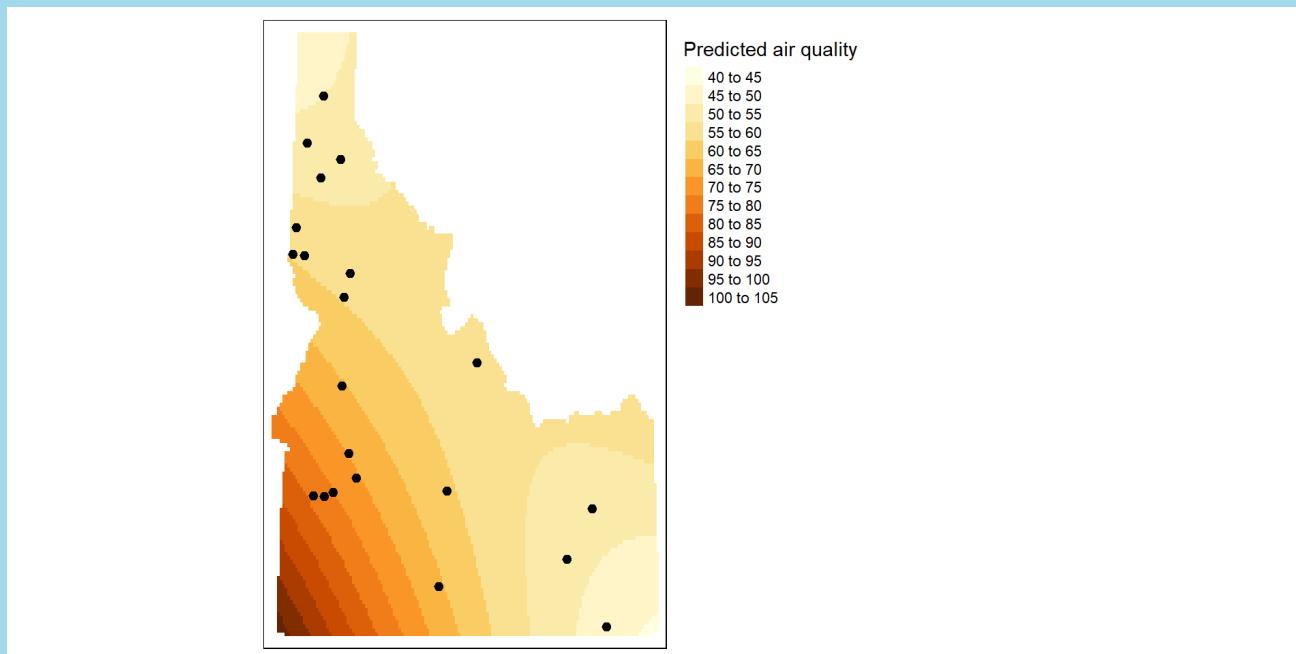


# 1st Order Trend Surface

```
1 # Define the polynomial equation
2 f.1 <- as.formula(meanpm25 ~ X + Y)
3
4 aq.sum$X <- st_coordinates(aq.sum) [,1]
5 aq.sum$Y <- st_coordinates(aq.sum) [,2]
6
7 # Run the regression model
8 lm.1 <- lm( f.1 , data=aq.sum)
9
10 # Use the regression model output to interpolate the surface
11 grd$var1.pred <- predict(lm.1, newdata = grd)
12 # Use data.frame without geometry to convert to raster
13 dat.1st <- grd %>%
14   select(X, Y, var1.pred) %>%
15   st_drop_geometry()
16
17 # Convert to raster object to take advantage of rasterVis' imaging
18 # environment
```

# 2nd Order Trend Surfaces

- Produces a parabolic surface
- $Z = a + bX + cY + dX^2 + eY^2 + fXY$
- Highlights the interaction of both directions



# 2nd Order Trend Surfaces

```
1 # Define the 1st order polynomial equation
2 f.2 <- as.formula(meanpm25 ~ X + Y + I(X*X)+I(Y*Y) + I(X*Y))
3
4 # Run the regression model
5 lm.2 <- lm( f.2, data=aq.sum)
6
7 # Use the regression model output to interpolate the surface
8 grd$var2.pred <- predict(lm.2, newdata = grd)
9 # Use data.frame without geometry to convert to raster
10 dat.2nd <- grd %>%
11   select(X, Y, var2.pred) %>%
12   st_drop_geometry()
13
14 r <- rast(dat.2nd, crs = crs(grd))
15 r.m <- mask(r, st_as_sf(id.cty))
16
17 tm_shape(r.m) + tm_raster(n=10, title="Predicted air quality") +
18   tm_shape(aq.sum) +
```

# Kriging

- Previous methods predict  $z$  as a (weighted) function of distance
- Treat the observations as perfect (no error)
- If we imagine that  $z$  is the outcome of some spatial process such that:

$$z(\mathbf{x}) = \mu(\mathbf{x}) + \epsilon(\mathbf{x})$$

then any observed value of  $z$  is some function of the process ( $\mu(\mathbf{x})$ ) and some error ( $\epsilon(\mathbf{x})$ )

- Kriging exploits autocorrelation in  $\epsilon(\mathbf{x})$  to identify the trend and interpolate accordingly

# Autocorrelation

- **Correlation** the tendency for two variables to be related
- **Autocorrelation** the tendency for observations that are closer (in space or time) to be correlated
- **Positive autocorrelation** neighboring observations have  $\epsilon$  with the same sign
- **Negative autocorrelation** neighboring observations have  $\epsilon$  with a different sign (rare in geography)

# Ordinary Kriging

- Assumes that the deterministic part of the process ( $\mu(\mathbf{x})$ ) is an unknown constant ( $\mu$ )

$$z(\mathbf{x}) = \mu + \epsilon(\mathbf{x})$$

# Steps for Ordinary Kriging

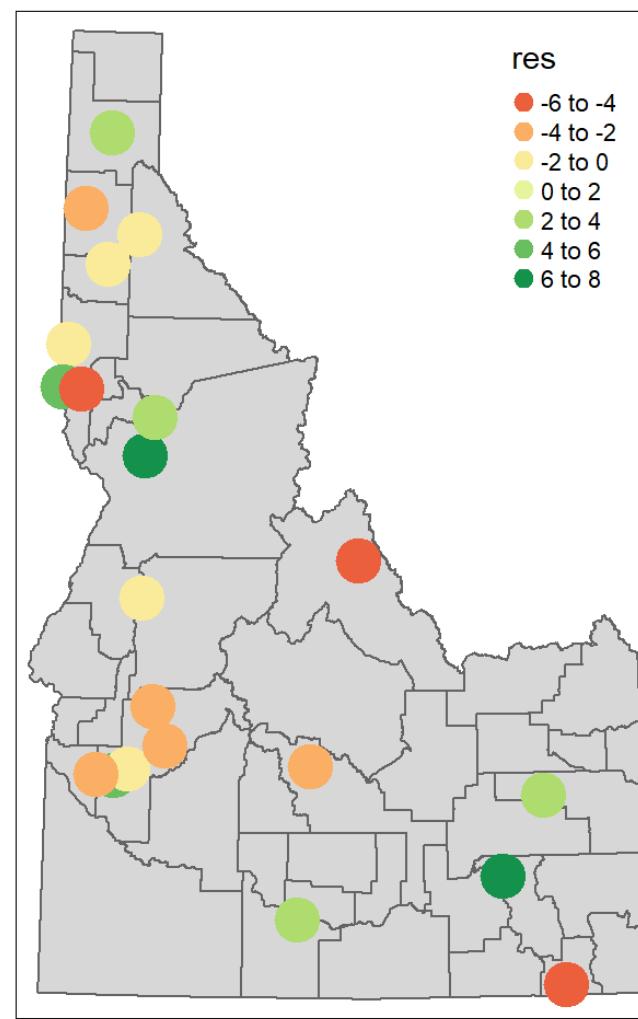
- Removing any **spatial trend** in the data (if present).
- Computing the **experimental variogram**,  $\gamma$ , which is a measure of spatial autocorrelation.
- Defining an **experimental variogram model** that best characterizes the spatial autocorrelation in the data.
- Interpolating the surface using the experimental variogram.
- Adding the kriged interpolated surface to the trend interpolated surface to produce the final output.

# Removing Spatial Trend

- Mean and variance need to be constant across study area
- Trend surfaces indicate that is not the case
- Need to remove that trend

```
1 f.2 <- as.formula(meanpm25 ~ X + Y + I(X*X)+I(Y*Y) + I(X*Y))  
2  
3 # Run the regression model  
4 lm.2 <- lm( f.2, data=aq.sum)  
5  
6 # Copy the residuals to the point object  
7 aq.sum$res <- lm.2$residuals
```

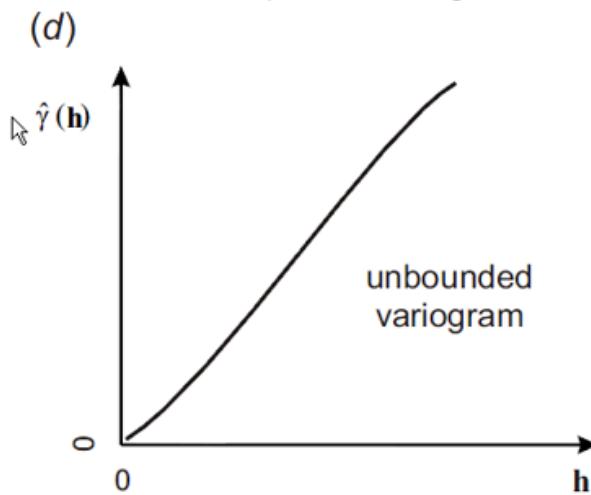
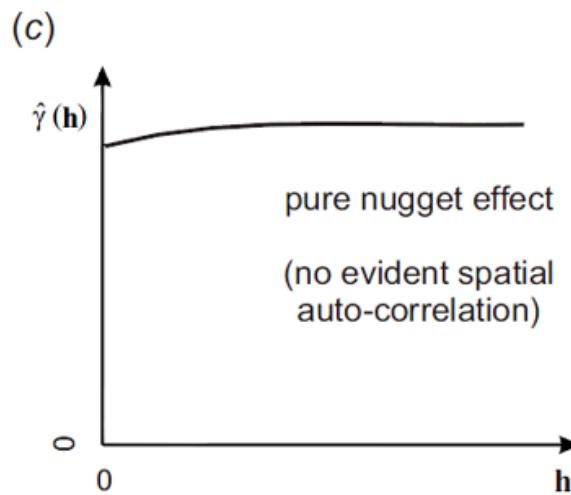
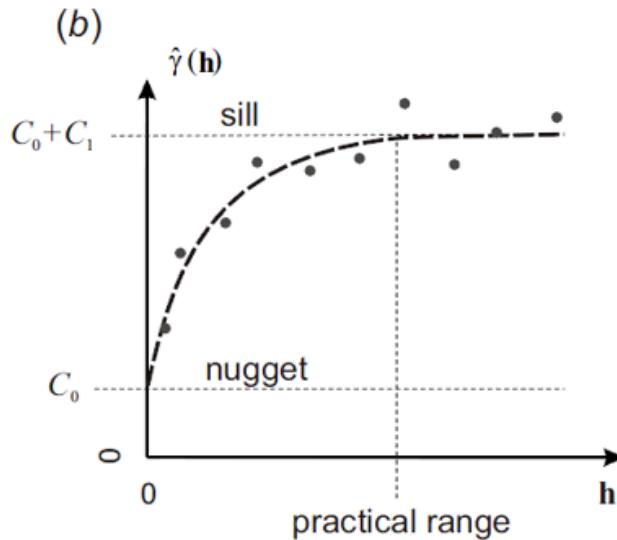
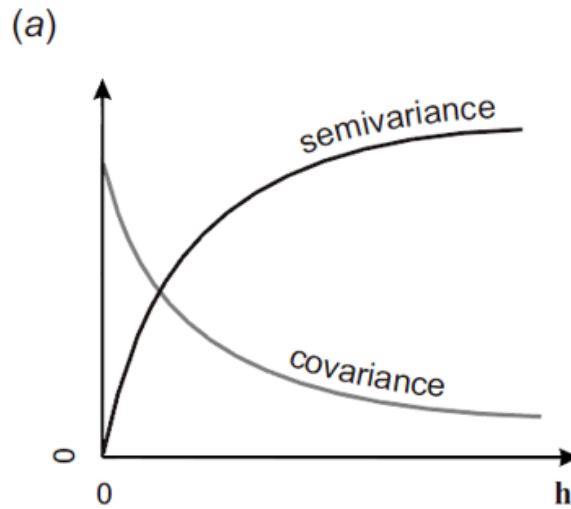
# Removing the trend



# Calculate the experimental variogram

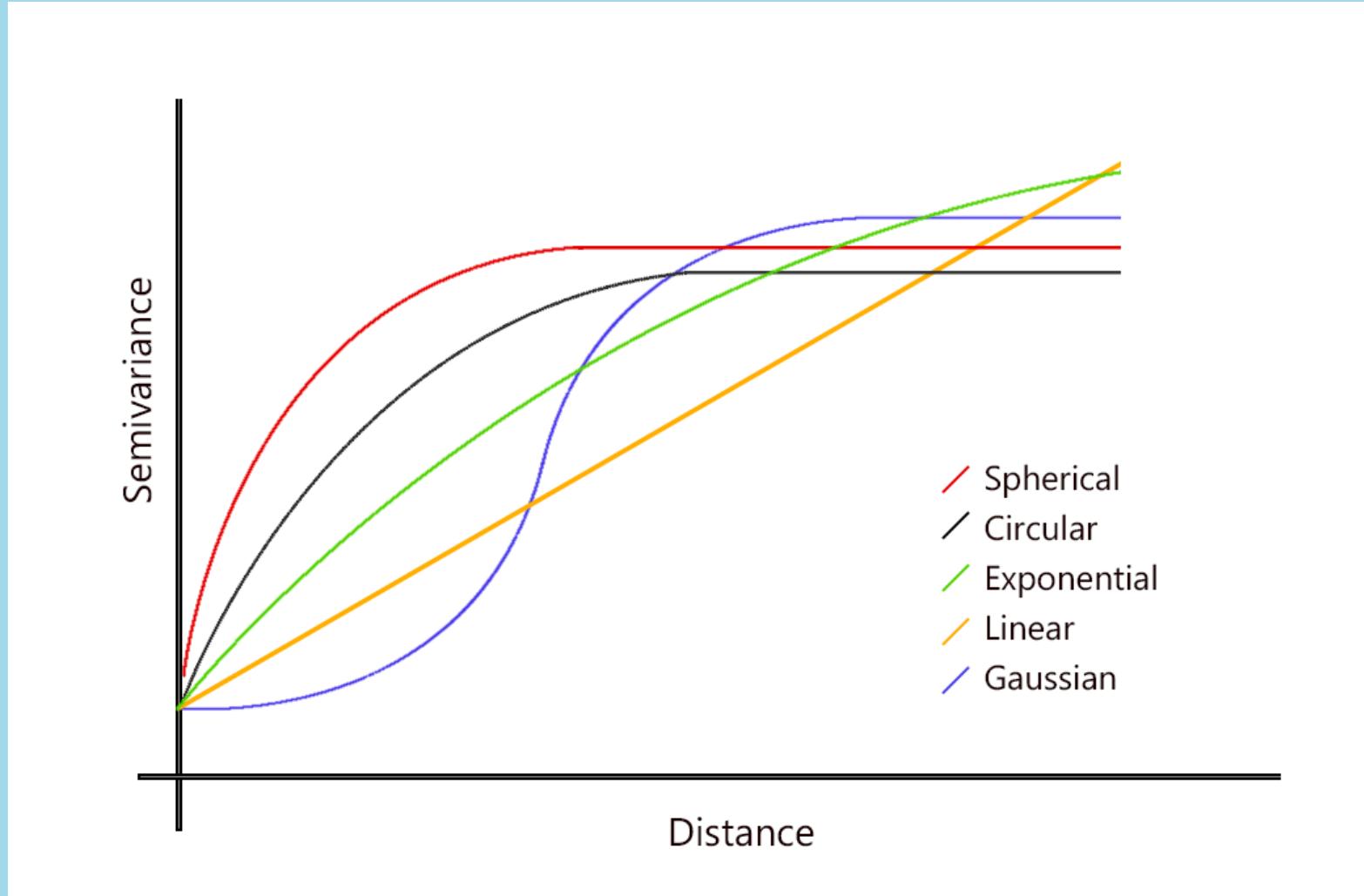
- **nugget** - the proportion of semivariance that occurs at small distances
- **sill** - the maximum semivariance between pairs of observations
- **range** - the distance at which the sill occurs
- **experimental vs. fitted** variograms

# A Note about Semivariograms



# Fitted Semivariograms

- Rely on functional forms to model semivariance



# Calculate the experimental variogram

```
1 var.cld <- gstat::variogram(res ~ 1, aq.sum, cloud = TRUE)
2 var.df <- as.data.frame(var.cld)
3 index1 <- which(with(var.df, left==21 & right==2))
```

# Calculate the experimental variogram

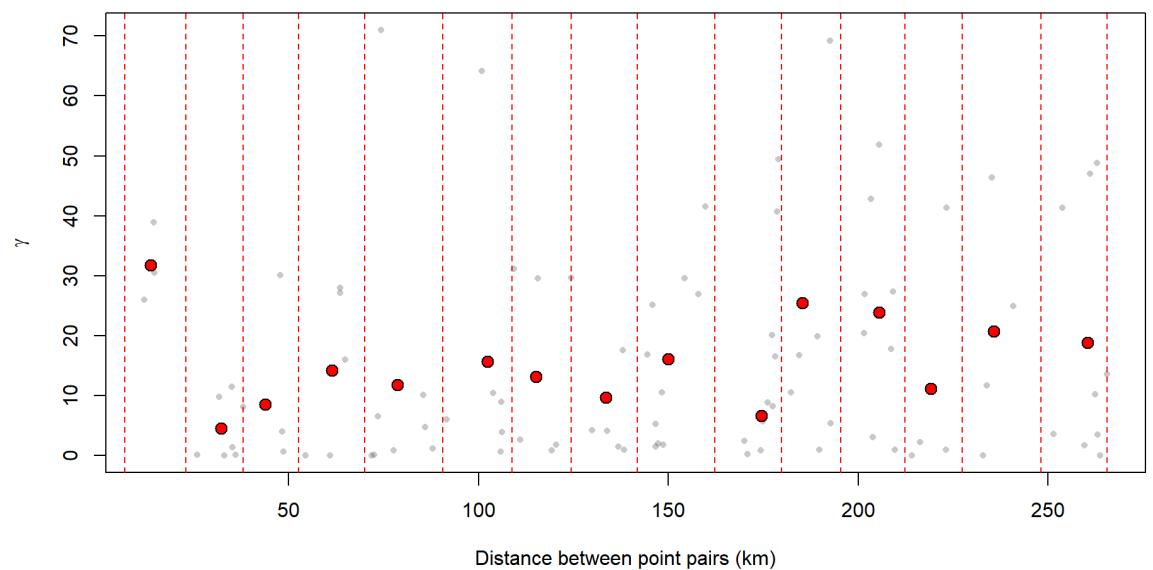
```
1 OP <- par( mar=c(4,6,1,1))  
2 plot(var.cld$dist/1000 , var.cld$gamma, col="grey",  
3       xlab = "Distance between point pairs (km)",  
4       ylab = expression( frac((res[2] - res[1])^2 , 2)) )  
  
1 par(OP)
```

# Simplifying the cloud plot

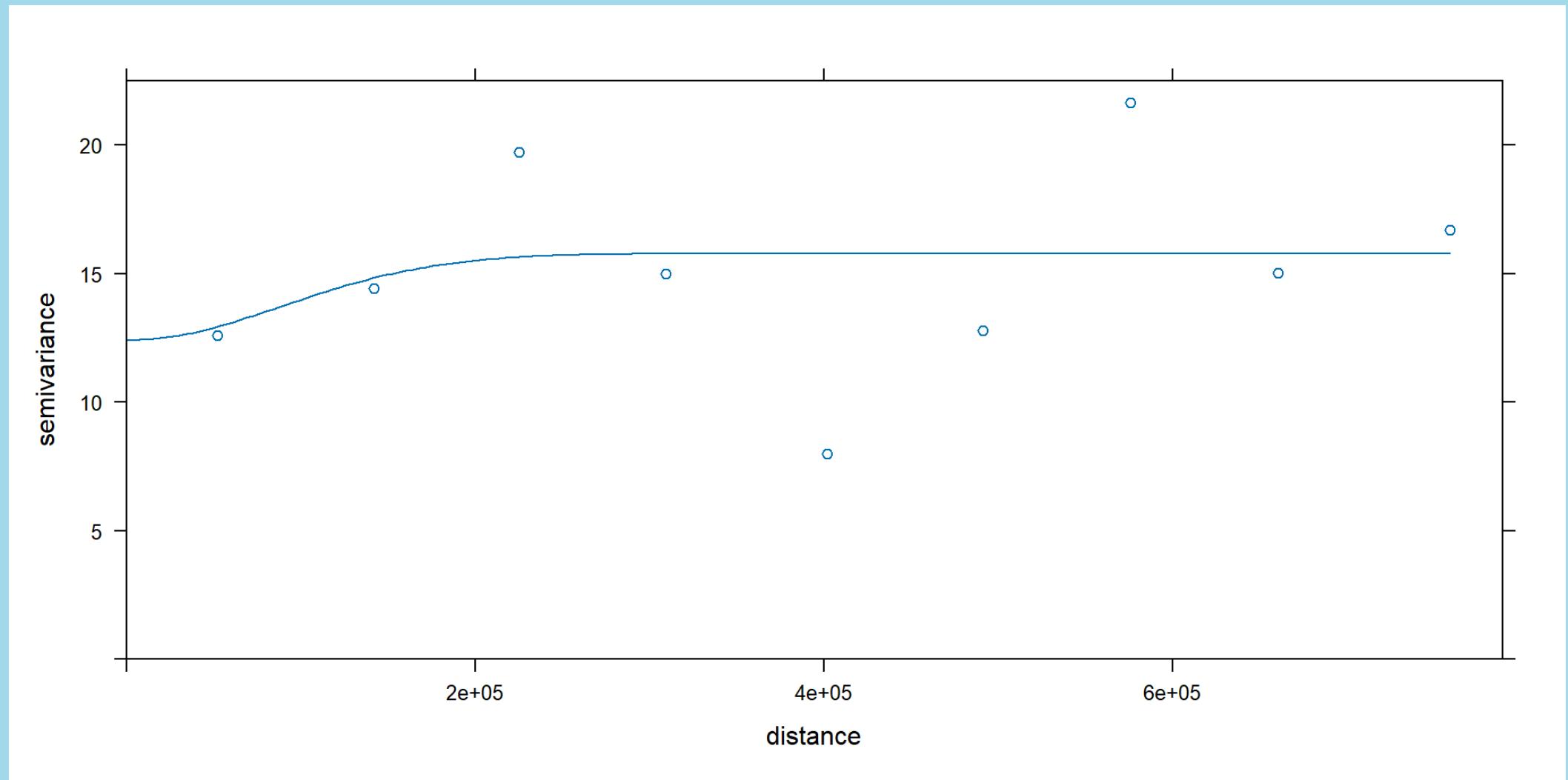
```
1 # Compute the sample experimental variogram  
2 var.smpl <- gstat::variogram(f.2, aq.sum, cloud = FALSE)  
3  
4 bins.ct <- c(0, var.smpl$dist , max(var.cld$dist) )  
5 bins <- vector()  
6 for (i in 1: (length(bins.ct) - 1) ) {  
7   bins[i] <- mean(bins.ct[ seq(i,i+1, length.out=2) ] )  
8 }  
9 bins[length(bins)] <- max(var.cld$dist)  
10 var.bins <- findInterval(var.cld$dist, bins)
```

# Simplifying the cloud plot

```
1 # Point data cloud with bin boundaries
2 OP <- par( mar = c(5, 6, 1, 1))
3 plot(var.cld$gamma ~ eval(var.cld$dist/1000), col=rgb(0,0,0,0.2), pch=16, c
4       xlab = "Distance between point pairs (km)",
5       ylab = expression( gamma ) )
6 points( var.smpl$dist/1000, var.smpl$gamma, pch=21, col="black", bg="red",
7 abline(v=bins/1000, col="red", lty=2)
1 par(OP)
```



# Looking at the sample Variogram

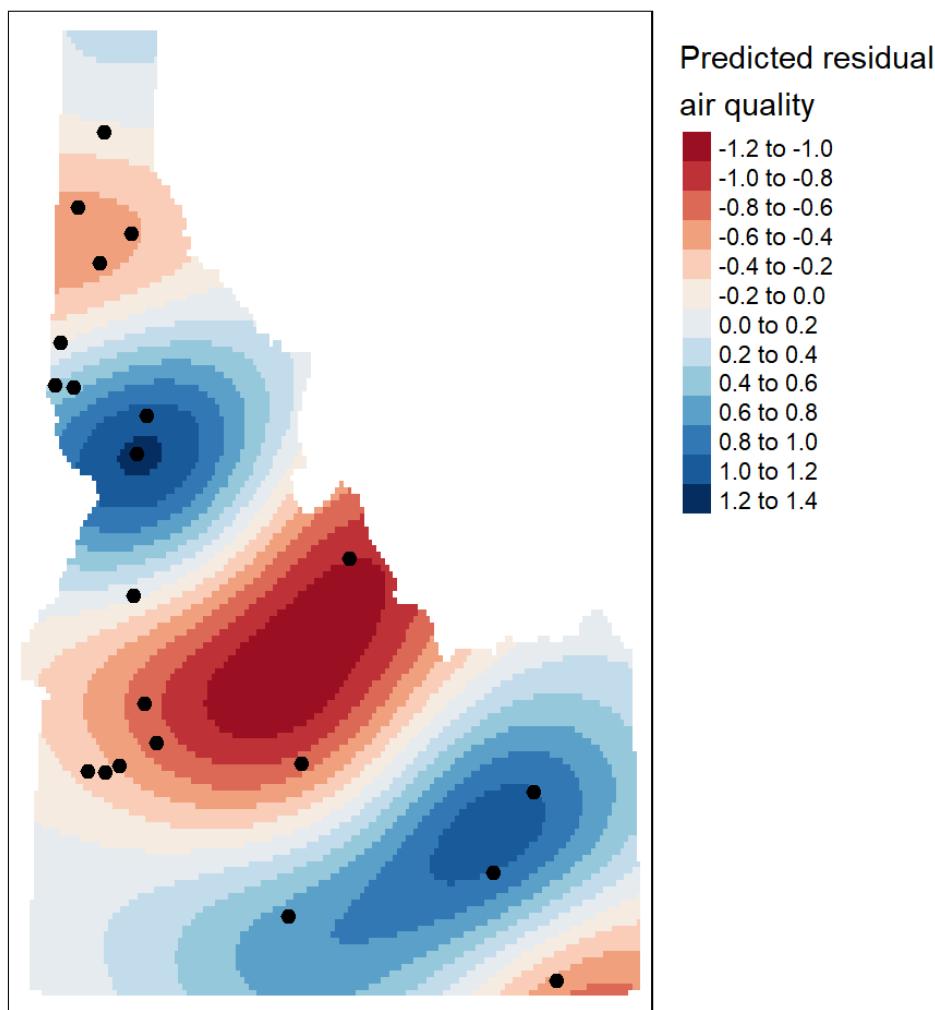


# Estimating the sample variogram

```
1 # Compute the sample variogram, note the f.2 trend model is one of the para  
2 # passed to variogram(). This tells the function to create the variogram on  
3 # the de-trended data  
4 var.smpl <- gstat::variogram(f.2, aq.sum, cloud = FALSE, cutoff = 1000000,  
5  
6  
7 # Compute the variogram model by passing the nugget, sill and range values  
8 # to fit.variogram() via the vgm() function.  
9 dat.fit <- gstat::fit.variogram(var.smpl, gstat::vgm(nugget = 12, range= 6  
10  
11 # The following plot allows us to gauge the fit  
12 plot(var.smpl, dat.fit)
```

# Ordinary Kriging

[using ordinary kriging]

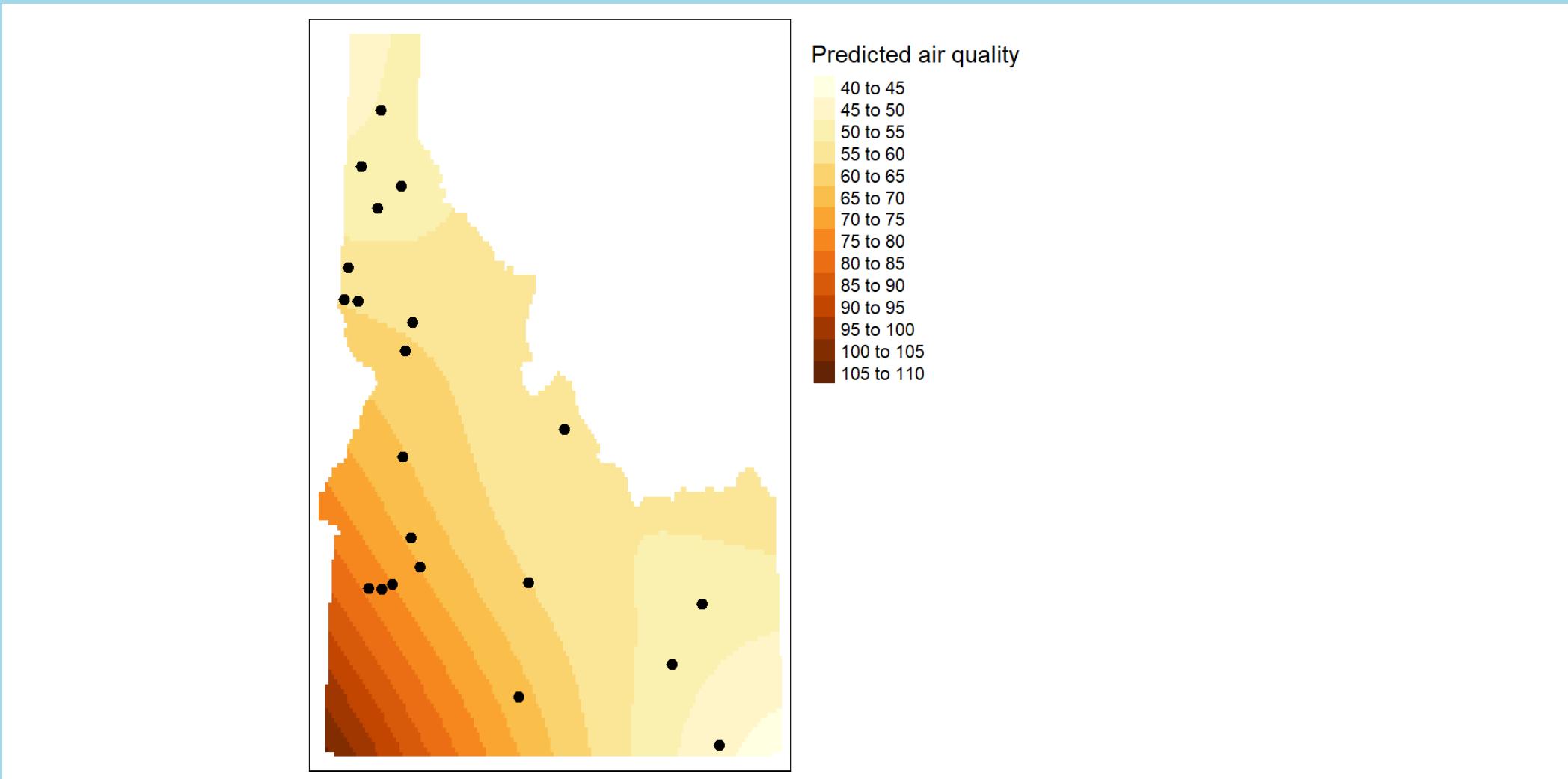


# Ordinary Kriging

```
1 dat.krg <- gstat::krige( formula = res~1,  
2                           locations = aq.sum,  
3                           newdata = grd[, c("X", "Y", "var2.pred")],  
4                           model = dat.fit)
```

# Combining with the trend data

[using universal kriging]



# Combining with the trend data

```
1 dat.krg <- gstat::krige( formula = f.2,
2                           locations = aq.sum,
3                           newdata = grd[, c("X", "Y", "var2.pred")],
4                           model = dat.fit)
5
6 dat.krg.preds <- dat.krg %>%
7   mutate(X = st_coordinates(.)[, 1],
8         Y = st_coordinates(.)[, 2]) %>%
9   select(X, Y, var1.pred) %>%
10  st_drop_geometry()
11
12 r <- rast(dat.krg.preds, crs = crs(grd))
13 r.m <- mask(r, st_as_sf(id.cty))
14
15 # Plot the raster and the sampled points
16 tm_shape(r.m) + tm_raster(n=10, title="Predicted air quality") +tm_shape(aq)
17   tm_legend(legend.outside=TRUE)
```

# Visualizing Uncertainty

